

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L3	425	(73/865.4 600/595 901/1 901/9 901/10 901/46 414/1 414/2).ccls.	US-PGPUB	OR	ON	2008/04/10 11:07
L5	26	(74/480r 74/490.07 74/490.11).ccls. not 3	US-PGPUB	OR	ON	2008/04/10 11:22
L6	2361	(73/865.4 600/595 901/1 901/9 901/10 901/46 414/1 414/2).ccls.	USPAT	OR	ON	2008/04/10 11:31
L7	507	(74/480r 74/490.07 74/490.11).ccls. not 6	USPAT	OR	ON	2008/04/10 11:40
L8	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	US-PGPUB	OR	ON	2008/04/10 11:41

L9	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder) with (((angular angle angularly) near (position positioning positioned)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	USPAT	OR	ON	2008/04/10 11:42
L10	1	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated	US-PGPUB	OR	ON	2008/04/10 11:42

		rotating rotor) near5 joint)))				
L11	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) with (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing)) near10 ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)))	USPAT	OR	ON	2008/04/10 11:43
L12	2	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position	US-PGPUB	OR	ON	2008/04/10 11:43

		positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))				
L13	0	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint) and ((rigid rigidly) near5 (link linking linled linker))	USPAT	OR	ON	2008/04/10 11:48

L14	8	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)	US-PGPUB	OR	ON	2008/04/10 11:48
L15	5	((exoskeleton exoskeletally exoskeletal) near5 (interface interfacing interfaced)) and ((measure measured measurement measuring measurer encoder monitor monitoring monitored detect detection detector detecting detected) near10 (((angular angle angularly) near (position positioning positioned	USPAT	OR	ON	2008/04/10 11:51

		movement moved move moving)) (posture postured posturing))) and ((rotation rotational rotationally rotate rotary rotatable rotatably rotated rotating rotor) near5 joint)				
L17	1	"6974297".pn.	USPAT	OR	ON	2008/04/10 12:00

4/ 10/ 2008 12:03:04 PM

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wsp